

# Selected Topics – Embedded Systems

## Midterm #1 - November 2011

**Model Answer**

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**Solve As Much As You Can – Maximum Grade:100 points**

### **Part 1. Answer the following questions by marking the best answer among the choices given: [3 points each]**

1. Using a 3.3V microcontroller, a GPIO pin can provide high current output using ...
    - a. A push-pull output mode
    - b. An open-drain output mode with internal weak pull-ups
    - c. An open-drain output mode with external pull-ups. (\*)
  2. Using a 3.3V microcontroller, one can make a GPIO work as an input pin using ...
    - a. An open-drain output mode and a pull-up resistor
    - b. A push-pull output mode and an amplifier at the output of the pin
    - c. A push-pull output mode and an internal weak pull-up (\*)
  3. For multiple microcontrollers to be synchronized, a clock source for C8051F020 based on ... is used.
    - a. RC oscillator
    - b. CMOS clock (\*)
    - c. Internal clock
  4. Accessing C8051F020 memory location 020H using indirect addressing mode refers to ...
    - a. Special function register
    - b. General purpose data RAM memory address (\*)
    - c. Immediate value
  5. Using a 3.3V microcontroller, a GPIO pin can provide TTL-compatible output levels using ...
    - a. A push-pull output mode (\*)
    - b. A push-pull output mode with internal weak pull-ups
    - c. An open-drain output mode
  6. We can toggle bit 3 of P1 by the following C instruction ...
    - a.  $P1 = P1 \wedge 008H$
    - b.  $P1 = P1 \& 0F7H$
    - c.  $P1.3 = \sim P1.3$  (\*)
  7. GPIO pins can be used for bidirectional data transfer when they are configured as ...
    - a. Open-drain mode with internal weak pull-ups (\*)
    - b. Open-drain mode with external pull-ups
    - c. Push-pull mode
  8. When the external crystal oscillator is invalid for a long period of time, the microcontroller ...
    - a. Switches automatically to internal oscillator
    - b. Can be configured to reset (\*)
    - c. Causes a flag to be raised for the program to repair the problem
  9. The instruction to be used to transfer data from program memory is ...
    - a. MOV
    - b. MOVX
    - c. MOVC (\*)
  10. C8051F020 has a ... architecture.
    - a. Harvard
    - b. Von Neumann
    - c. Mixed
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**Part 2. Mark the following statement as either True (T) or False (F): [1 Point each]**

11. C8051F020 is a mixed-signal microcontroller because it can handle analog and digital data. (F)
  12. The C8051F020 instruction MOV can be used with indirect addressing. (T)
  13. Microcontroller external clock configuration must perform a check on the external clock validity (T)
  14. Division must work only in register addressing mode. (T)
  15. Using bit to declare a bit variable is valid only for global variables (F)
  16. 8-bit MCUs are well-suited for low-power applications that use batteries. (T)
  17. One can declare a bit-addressable variable in C language programming for microcontrollers (F)
  18. The operands of a logical operation must be Boolean. (F)
  19. Some registers in 8-bit microcontrollers are 16-bit wide. (T)
  20. The size of the bit-addressable region of the data memory allows for 256 bit variables. (F)
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**Part 3. Denote the following C8051F020 microcontroller instructions as either being true (T) or false (F) assembly instructions: [1 point each]**

21. MOV #70H, 060H (F)
  22. MOV @R0, A (T)
  23. ADD A, #030H (T)
  24. RLC 040H (F)
  25. DJNZ R7, 70H (T)
  26. CPL P2.4 (T)
  27. MAIN EQU 070H (F)
  28. POP 070H (T)
  29. XCH A, #05AH (F)
  30. DA A (F)
  31. CJNE R6, 70H (F)
  32. CPL P1^3 (F)
  33. SETB C (T)
  34. INC @R1 (T)
  35. MUL AB (T)
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**Part 4. Determine the number of bytes required to represent the following instructions in assembly: [2 points each]**

36. CLR A (1)
  37. RR A (1)
  38. MOV A, R4 (1)
  39. LJMP MAIN (3)
  40. ACALL ARRAY (2)
  41. JNZ Loop (2)
  42. CLR P1.1 (2)
  43. XRL P2, #40h (3)
  44. CPL A (1)
  45. RLC A (1)
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**Part 5. Compute the output of the following operations in a C Language program for a C8051F020 device: [2 points each]**

- 46. 00100100b > 10100001b (ans: FALSE)
- 47. !(00100100b | 00000001b) (ans: FALSE)
- 48. (0F0H & 080H) >= 0 (ans: TRUE)
- 49. 021H % 02H (ans: 1)
- 50. 1>>2 (ans: 0)
- 51. 0F0H + 00AH (ans: 0FAH )
- 52. !(00100100b & 00000001b) (ans: TRUE)
- 53. (0F0H - 080H) == 0 (ans: FALSE)
- 54. 0A3H % 08H (ans: 3)
- 55. 040H>>2 (ans: 010H)

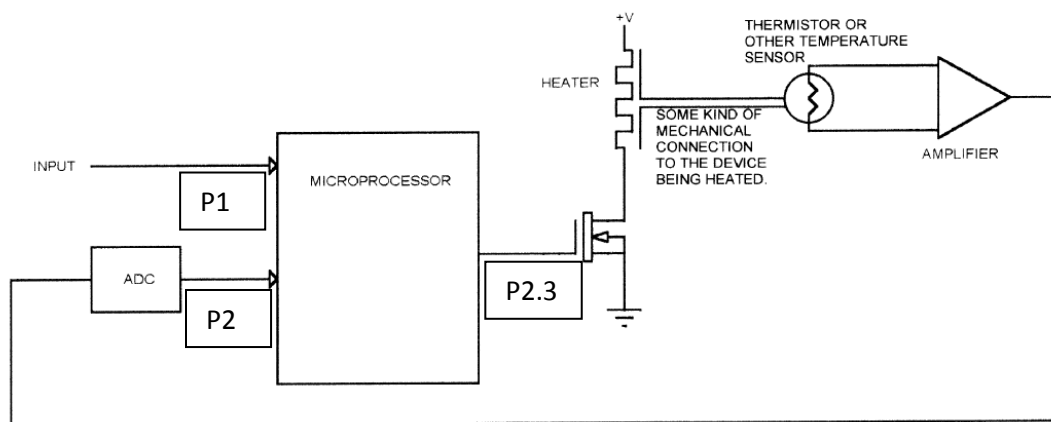
**Q6. Write C8051F020 assembly code lines to do the following: [4 Points each]**

- c. Configuration of external crystal oscillator working at 1 MHz.
- d. Generation of a periodic binary signal with duty cycle of 30% from pin P1.6.
- e. Transfer the contents of memory location 050H to accumulator A using 2 different methods.

**Answers: To Be Discussed in LAB**

**Part 7. [10 points]** Consider the simple C8051F020 microcontroller-based temperature control shown below. The user selects the value of the temperature and puts it as an 8-bit INPUT that is connected to PORT 1 while the temperature measured is converted to an 8-bit digital value and connected to PORT 2. The microcontroller can turn the heater ON by setting pin P2.3 and OFF by resetting the same pin. Design a project that would enable the ON/OFF control of the heater to adjust the temperature to exactly the value read by INPUT. Control should work as follows:

1. Read INPUT
2. Read ADC
3. Compare INPUT to ADC
4. Turn Heater ON if INPUT > ADC and wait for 1 s
5. Turn Heater OFF if INPUT < ADC



**Answer: To Be Discussed in LAB**